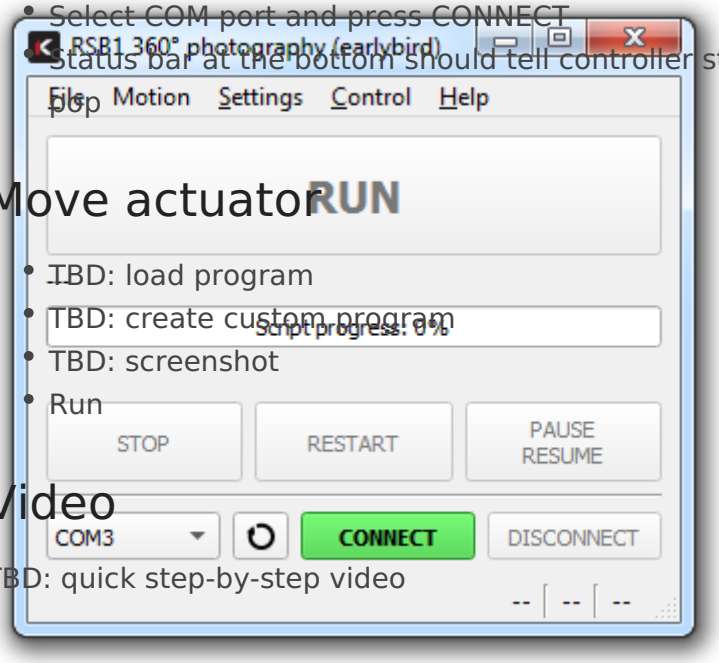
How to start using

Start program

- Connect actuator to port A
- Connect cables (USB and power)

TBD: picture

- Install serial port driver if needed STM32 Virtual COM Port Driver
- Download latest Windows release from GitHub
- Extract zip file and run **RSB1_360_photography** program
- You should be greeted with window



- Select COM port and press CONNECT
- Status bar at the bottom should tell controller status and version. Or error message will pop

Move actuator

- TBD: load program
- TBD: create custom program
- TBD: screenshot
- Run

Video

TBD: quick step-by-step video

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