

# SCE2-MOTION

Fully integrated 4 axis motion controller for automated photography

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# Overview

**SCE2-MOTION** is a compact controller designed for robotic photography, controls [motor actuators](#), and triggers DSLR camera. It is based on 4 channel stepper motor controller [SCE2-M](#) module. The controller is running open-source [GRBL firmware](#) capable of advanced scripting and complex movements.



# Dimensions

Compact design with extra heat dissipation capabilities.

- Dimensions: 64 x 58 x 16.5mm
- Weight: 87g

# Control software

**SCE2-MOTION** can be controlled by any G-code sender like [Candle](#), [Universal-G-Code-Sender](#), and many more. Most of these software packages lack the g-code generator part. So highly specialized open-source programs had to be created from scratch.

## RSB1 360 product photography

- Source code on GitHub
- Windows releases also on GitHub
- More details about motion control software

Code is written with Python it can be run on any modern operating system, even Raspberry Pi

# Default GRBL settings

Each actuator combination needs individual settings to be fine tuned. Below settings are for:

- **RSB1** connected to X axis
- **LSA1** connected to Y axis

GRBL settings for fastest speed under light load:

```
$0=6
$1=255
$2=0
$3=31
$4=1
$5=0
$6=0
$10=19
$11=0.010
$12=0.002
$13=0
$20=0
$21=0
$22=1
$23=15
$24=50.000
$25=200.000
$26=250
$27=5.000
$30=1000
$31=0
$32=0
$100=111.110
$101=5039.370
$102=111.110
$103=111.110
$110=20000.000
$111=2000.000
```

\$112=20000.000

\$113=20000.000

\$120=2000.000

\$121=100.000

\$122=2000.000

\$123=2000.000

\$130=360.000

\$131=90.00

\$132=360.000

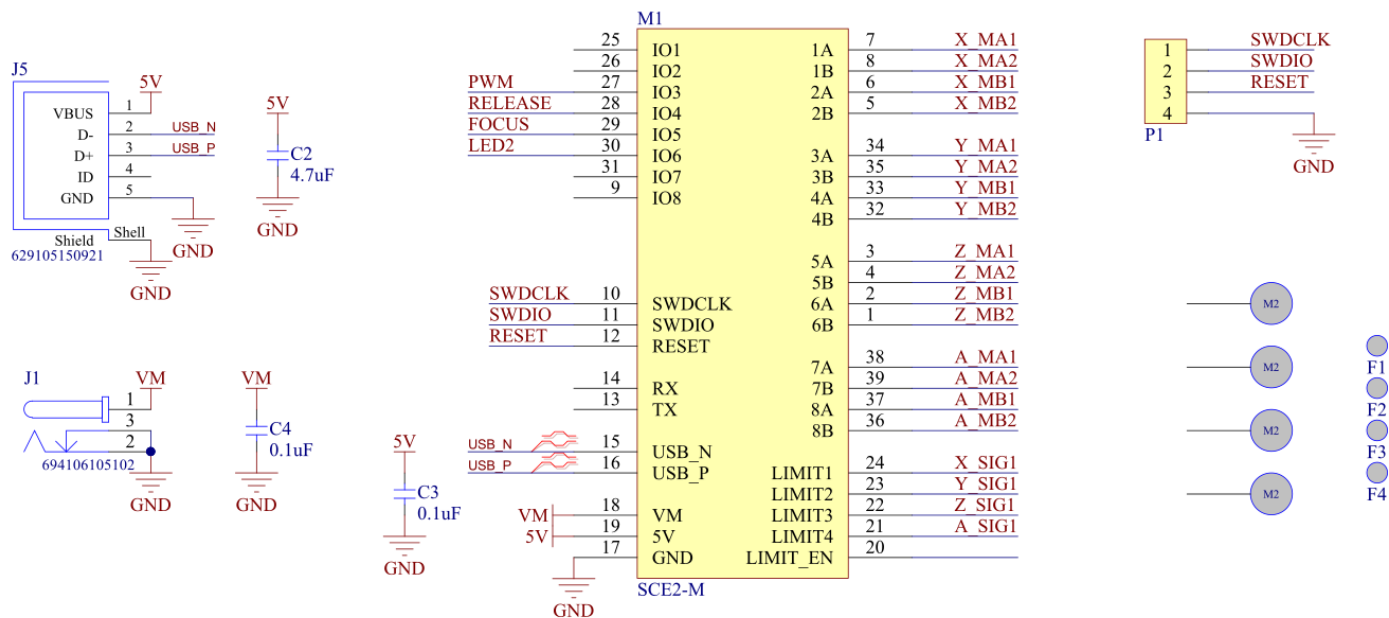
\$133=360.000

# Firmware

Firmware is open-source GRBL based running on STM32 microcontroller.

# Schematics

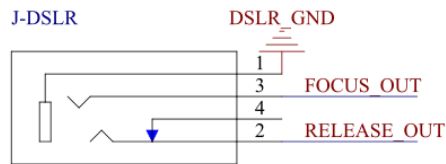
## SCE2-M module



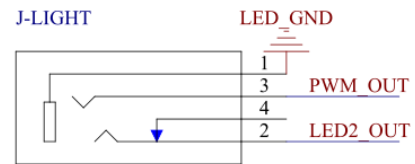
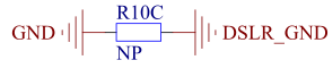
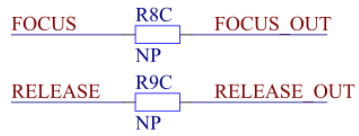
## DSLR control headers

SCE2-MOTION has 4 outputs available. Controller is shipped with connected optocouplers (safe to connect to expensive DSLR camera). But for ease of customization control signals can be wired directly. See not populated resistors.

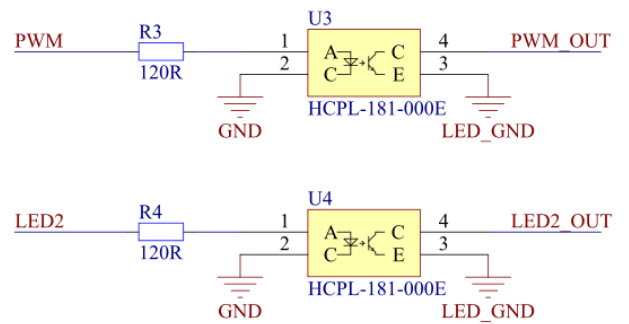
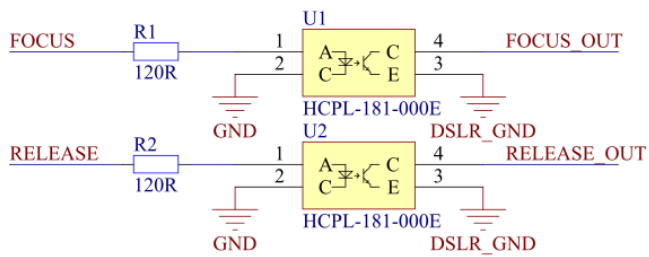
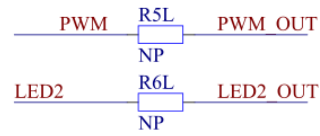




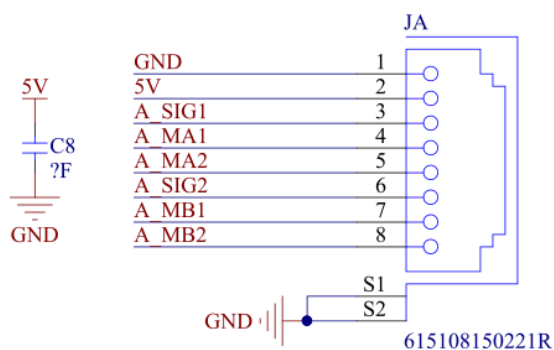
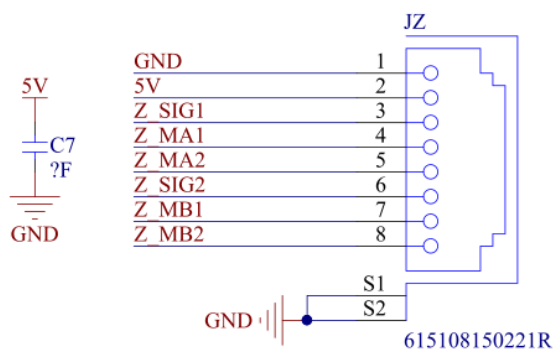
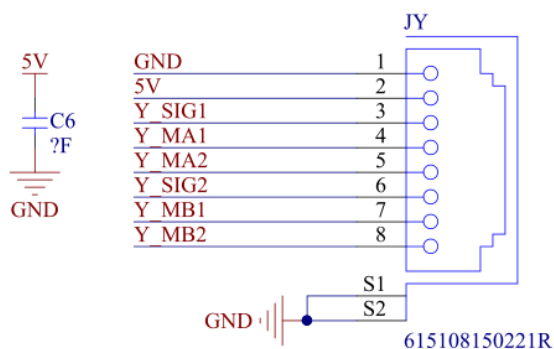
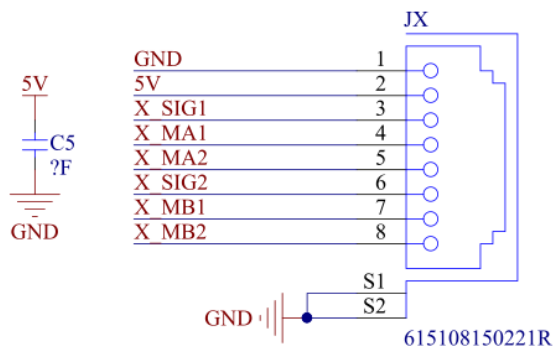
SJ1-2534-SMT



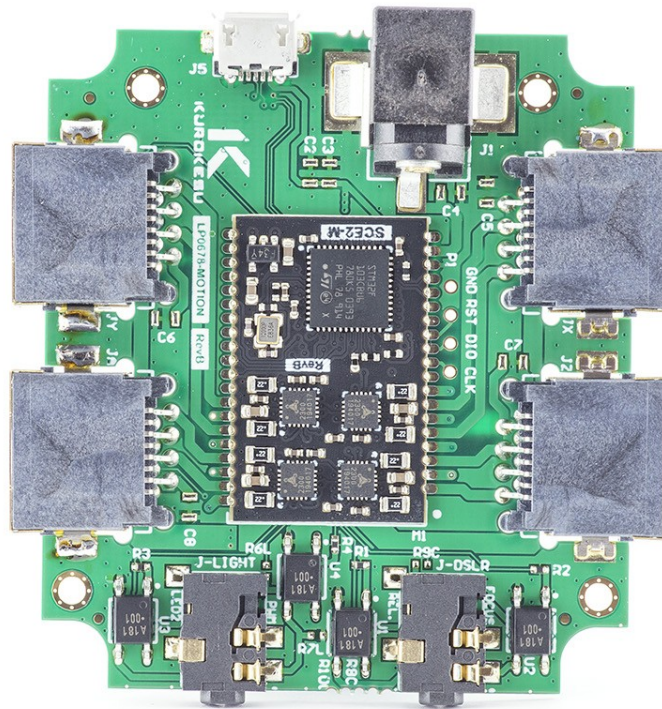
SJ1-2534-SMT



# Motor RJ45 headers



Top PCBA view



# Power supply

Controller can drive up to 1.2A per channel, thus max power demand when all 4 motors are driven at 100% power will not exceed 5A @ 9V DC.